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This article [*Opt. Eng.* **53**(6), 061610 (2014)] was originally published on 16 December 2013 with incorrect mathematical symbols in two equations. Equations 12 and 13 originally appeared as below:

$$\cos \gamma_2 = \frac{\operatorname{tg} \alpha \cos \varphi(x_2 - x_1) + \operatorname{tg} \alpha \sin \varphi(y_2 - y_1) - (z_2 - z_1)}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2} \sqrt{1 + \operatorname{tg}^2 \alpha}} \times \left(0 \leq \gamma_2 \leq \frac{\pi}{2} \right), \quad (12)$$

$$\cos \eta_2 = \frac{-(z_2 - z_1)}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}} \times \left(0 \leq \eta_2 \leq \frac{\pi}{2} \right). \quad (13)$$

The corrected equations are:

$$\cos \gamma_2 = \frac{\operatorname{tg} \alpha \cos \varphi(x_2 - x_1) + \operatorname{tg} \alpha \sin \varphi(y_2 - y_1) - (z_2 - z_1)}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2} \cdot \sqrt{1 + \operatorname{tg}^2 \alpha}} \quad \left(0 \leq \gamma_2 \leq \frac{\pi}{2} \right), \quad (12)$$

$$\cos \eta_2 = \frac{-(z_2 - z_1)}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}} \quad \left(0 \leq \eta_2 \leq \frac{\pi}{2} \right). \quad (13)$$

The paper was corrected online on 18 December 2013.